

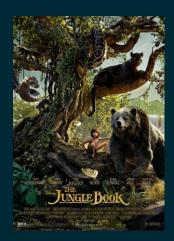
# Democratizing Deep Learning with Unity ML-Agents

Arthur Juliani

### About Unity

"Creation Engine"

- Games
- AR/VR
- Cinematics
- Simulations
- 40+ Platforms
- Free for personal use



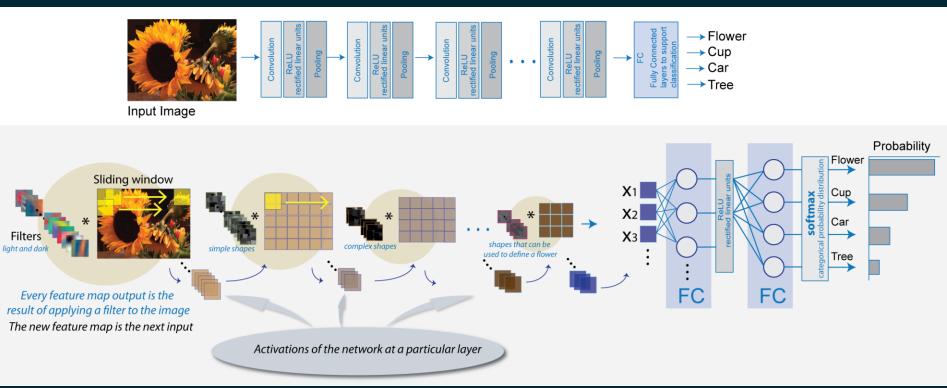






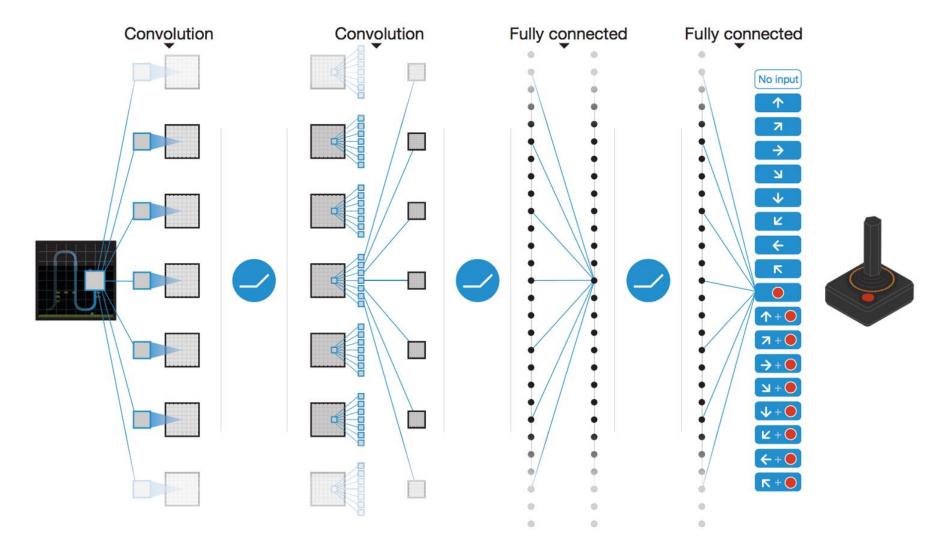


#### Machine Learning



## **Machine Learning And Games?**





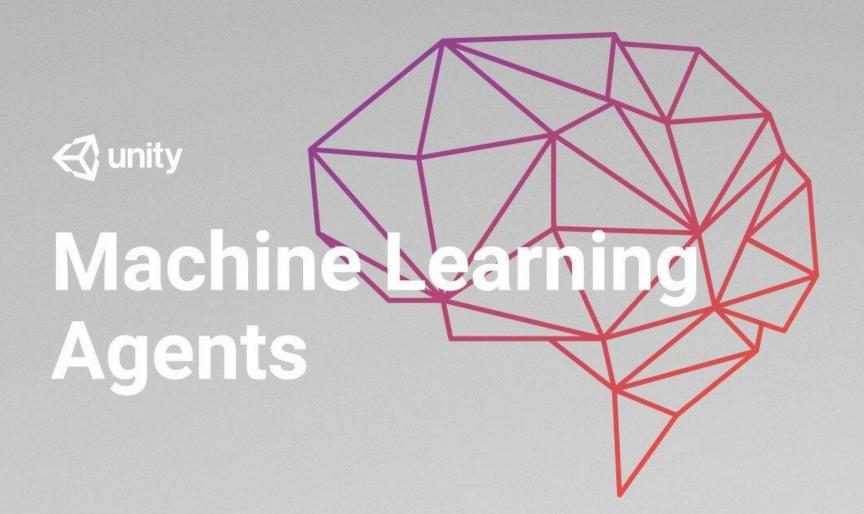


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## Yet another ML training platform?

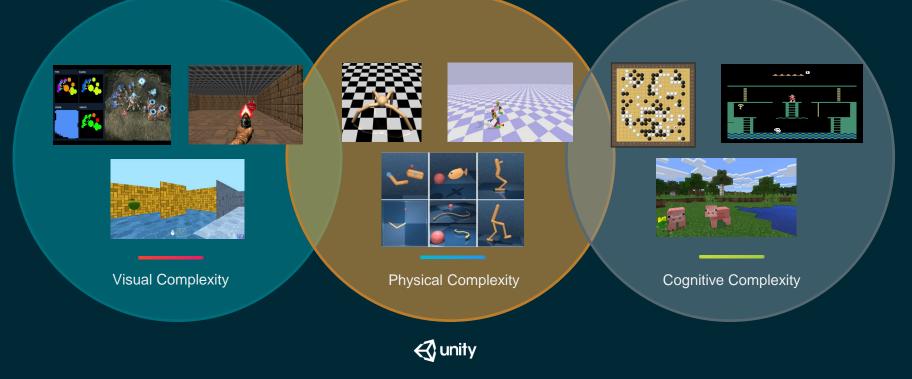


#### **ML Training Platforms**



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#### **ML Training Environments**



### The Unity Ecosystem













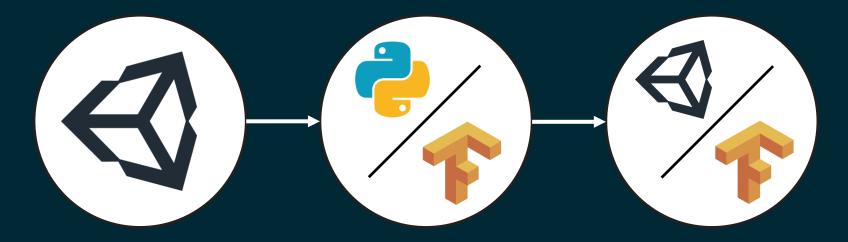




## How does it work?



### **Unity ML-Agents Workflow**

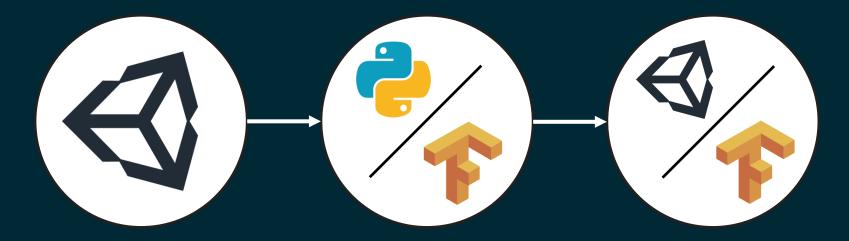


Create Environment

Train Agents

**Embed Agents** 

### **Unity ML-Agents Workflow**



**Create Environment** 

**Train Agents** 

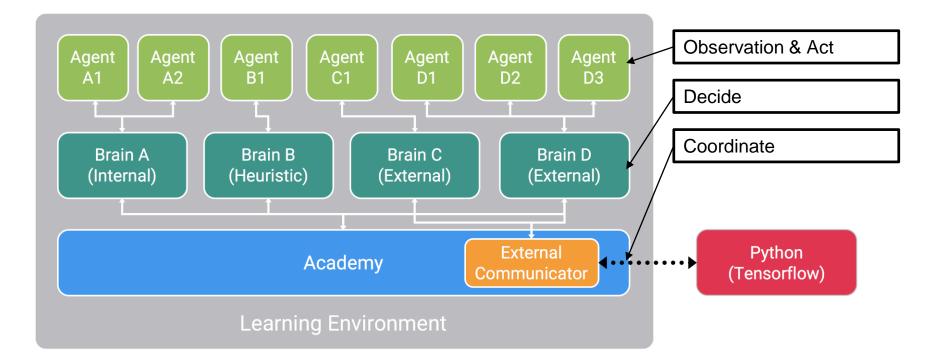
**Embed Agents** 

#### **Create Environment (Unity)**

- 1. Create Scene
- 2. Add Academy, Brain(s), and Agent(s)
- 3. Define Observations, Actions, and Rewards
- 4. Build Executable



### **Create Environment (Unity)**



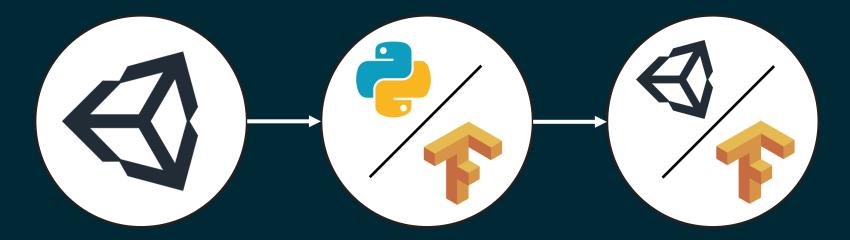
#### Agents

- Agents are GameObjects within the Unity scene.
- They perceive the environment via *observations*, take *actions*, and optionally receive *rewards*.
- Each agent is linked to a brain, which makes decisions for the agent.

#### **Brains**

- **Player** Actions are decided by user input through keyboard or gamepad.
- Heuristic Actions are decided by C# script using state input.
- External Actions are decided using Tensorflow via Python interface.
- Internal Actions are decided using Tensorflow model embedded into project.

### **Unity ML-Agents Workflow**



**Build Environment** 

Train Agents

**Embed Agents** 

### **Training Methods**

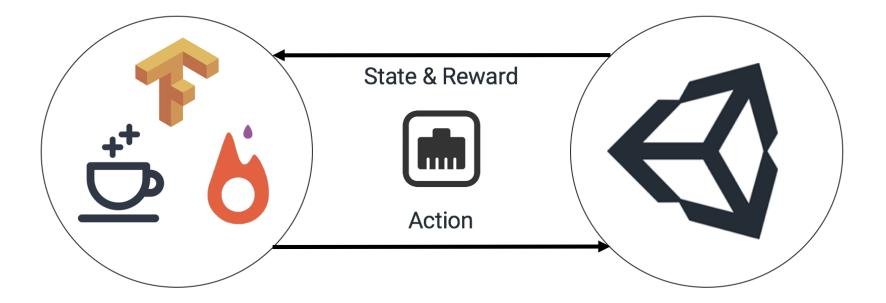
#### **Reinforcement Learning**

- Learn through rewards
- Trial-and-error
- Super-speed simulation
- Agent becomes "optimal" at task

#### **Imitation Learning**

- Learn through demonstrations
- No rewards necessary
- Real-time interaction
- Agent becomes "human-like" at task

### **Agent Training Process**



#### Train Agents (Python)

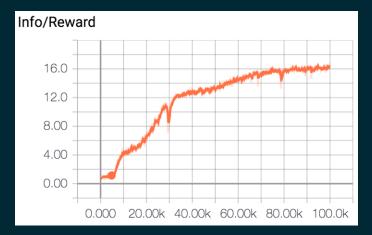
- Launch an environment from python with env = UnityEnvironment("my\_environment")
- Interact with gym-like interface:

env.reset()
env.step()
env.close()

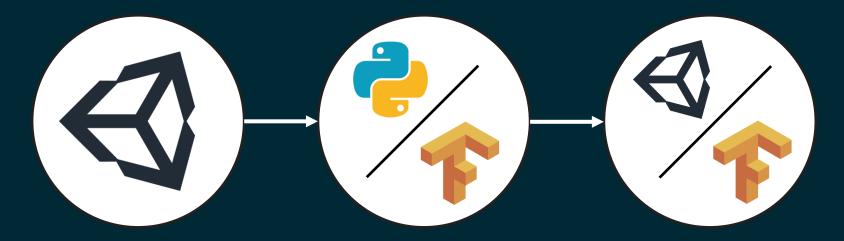
1 env = UnityEnvironment(file name=env name) 2 3 # Examine environment parameters print(str(env)) 6 # Set the default brain to work with 7 default brain = env.brain names[0] 8 brain = env.brains[default brain] INFO:unityagents.environment: 'Ball3DAcademy' started successfully! Unity Academy name: Ball3DAcademy Number of brains: 1 Reset Parameters : Unity brain name: Ball3DBrain Number of observations (per agent): 0 State space type: continuous State space size (per agent): 8 Action space type: continuous Action space size (per agent): 2 Memory space size (per agent): 0

#### Train Agents (Python)

- PPO and Behavioral Cloning algorithms included by default.
- Works with Continuous and Discrete Control, plus image and/or vector inputs.
- Monitor progress with TensorBoard.



### **Unity ML-Agents Workflow**



**Build Environment** 

Train Agents

**Embed Agents** 

🚭 unity

#### Embed Agents (Unity)

- Once a model is trained, it can be exported into the Unity project.
- Simply drop *.bytes* file into Unity project, and use it in corresponding Brain with "Internal" mode.
- Support for Mac, Windows, Linux, iOS, and Android.

	Wall.bytes	
ype Of Brain	Internal	÷
dit the Tensorflow graph parameters here		
raph Model	₩all	
raph Scope : atch Size Node Name	batch_size	
ate Node Name	state	
ecurrent Input Node Name	recurrent_in	
ecurrent Output Node Name	recurrent_out	
ction Node Name	action	
raph Placeholders		

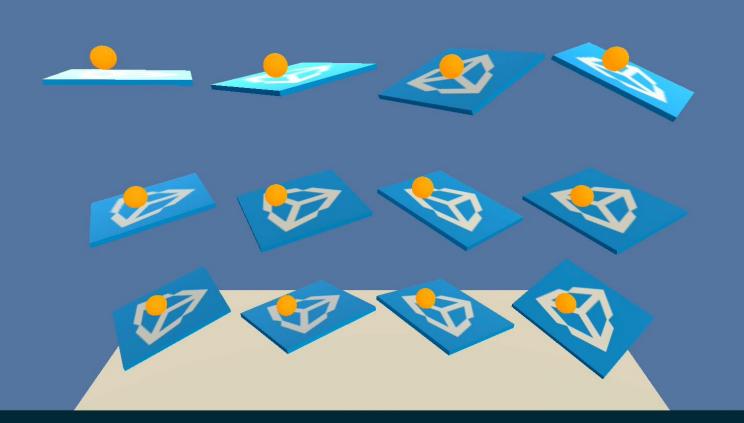
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## **Learning Scenarios**

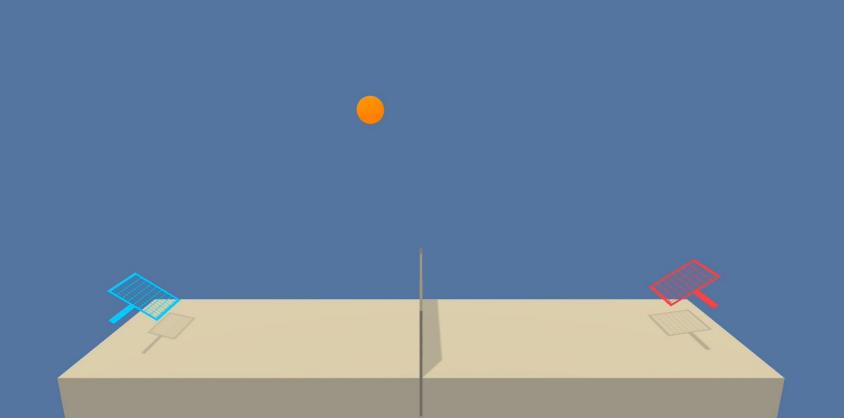


Twelve Agents, One Brain, Independent Rewards

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## Two Agents, One Brain, Cooperative Rewards



## Four Agents, Two Brains: Competitive Multi-Agent

#### **Multi-Stage Soccer Training**

#### Defense

Train one brain with negative reward for ball entering their goal

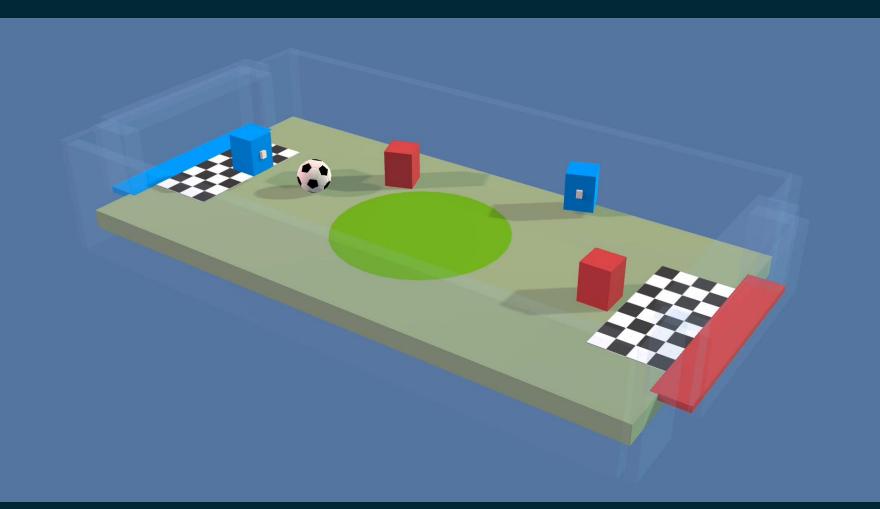
#### Offense

Train one brain with positive reward for ball entering opponents goal

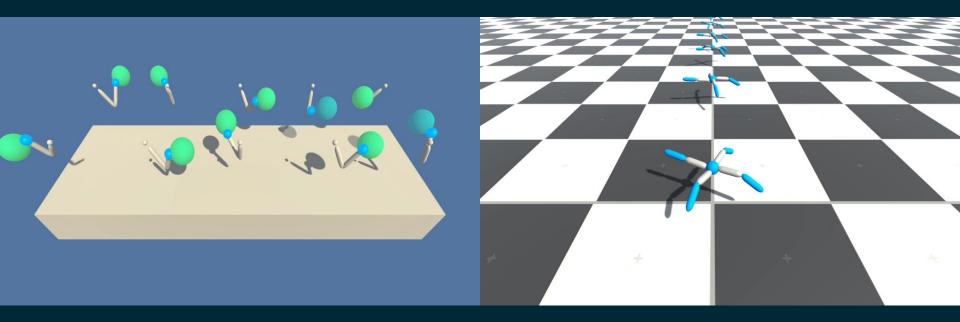
#### Combined

Train both brains together to play against opponent team





#### **Physical Manipulation**



Reacher



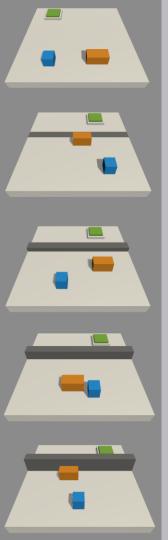
Crawler

## **Additional Features**



## **Curriculum Learning**



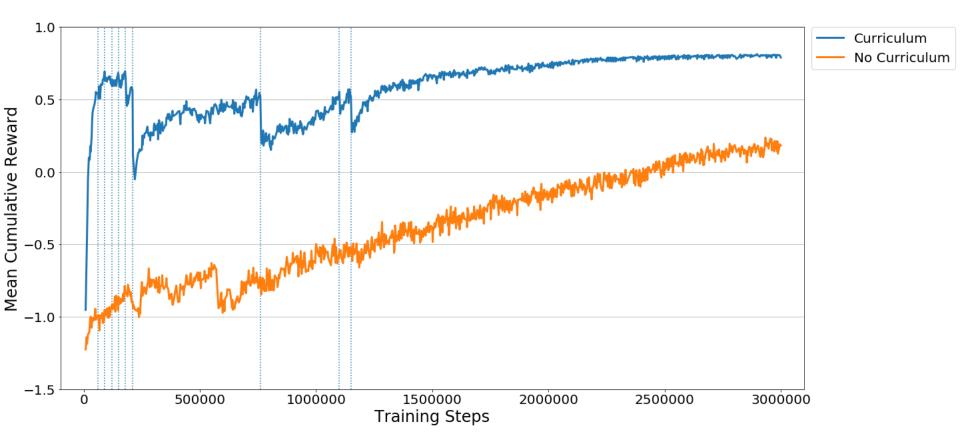


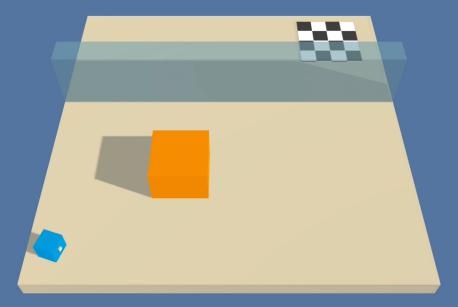
#### Difficult

Easy

#### **Curriculum Learning**

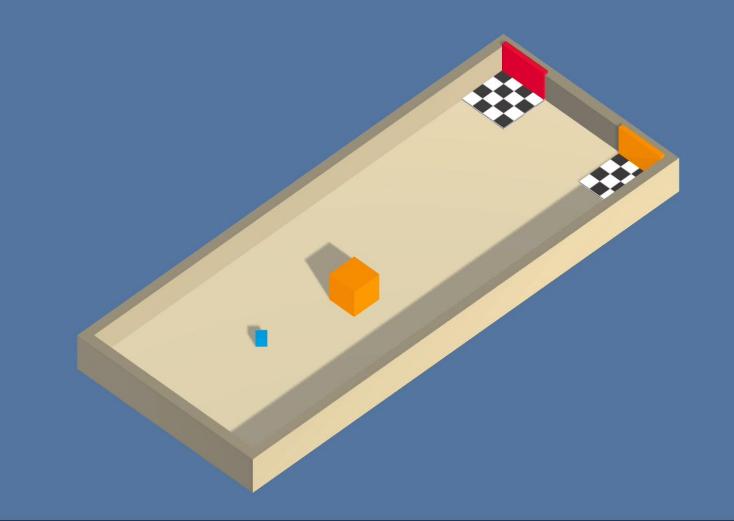
- Bootstrap learning of difficult task with simpler task
- Utilize custom reset
   parameters
- Change environment task based on reward or fixed progress



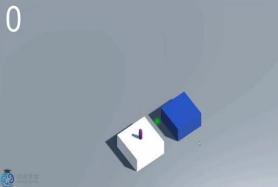




### Memory-enhanced agents





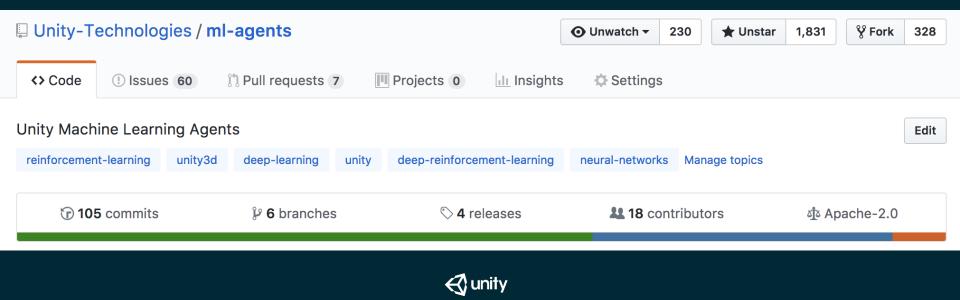








#### **Try it Now** *https://github.com/Unity-Technologies/ml-agents*





# Thank You! Questions?